

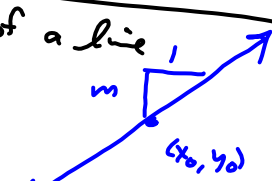
$\vec{\tau} = \text{Torque} = \vec{b} \times \vec{F}$   
 $\vec{b}$  is kind of in  $yz$ -plane  
 $\vec{F}$  .. .. ..  $xy$ -plane  
 $\vec{\tau}$  .. .. .. into the screen.  
 $\vec{\tau}$  is axis of rotation  
 $\|\vec{\tau}\|$  .. its tendency to rotate

Recall: Point-slope form of a line

$$y - y_0 = m(x - x_0)$$

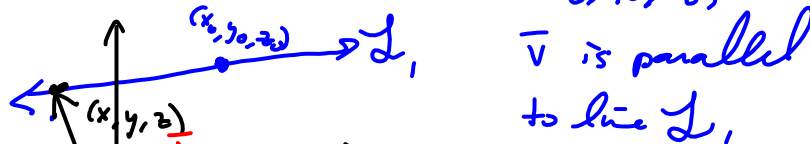
My Way:  $y = m(x - x_0) + y_0$

is a line thru  $(x_0, y_0)$  with slope  $m$



"A line is a point (position vector) PLUS some multiple of a vector parallel to the line"

$$\vec{r}_0 = \langle x_0, y_0, z_0 \rangle \leftrightarrow P(x_0, y_0, z_0)$$



$\vec{v}$  is parallel to line  $L_1$

$$\vec{b} = \langle x, y, z \rangle$$

$$= \langle x_0, y_0, z_0 \rangle + t\vec{v} \text{ (from pic.)}$$

In general

$$\vec{b} = \vec{r}_0 + t\vec{v} \text{ for all } \vec{b} \text{ on the line.}$$

$$= \vec{b} = \langle x_0, y_0, z_0 \rangle + t \langle v_1, v_2, v_3 \rangle \text{ for some } t \in \mathbb{R}$$

$$x = x_0 + tv_1, \quad y = y_0 + tv_2, \quad z = z_0 + tv_3$$

Parametric equations for  $L_1$

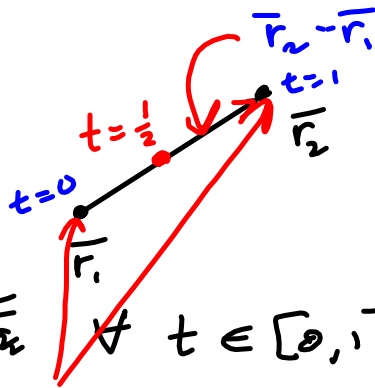
$$x - x_0 = tv_1$$

$$\frac{x - x_0}{v_1} = t = \frac{y - y_0}{v_2} = \frac{z - z_0}{v_3}$$

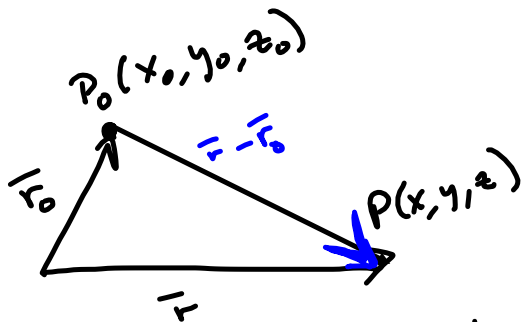
Symmetric Eqns for the line.

Line Segment between 2 points (position vectors):

$$\vec{r}_1 \text{ \& \ } \vec{r}_2$$



$$(1-t)\vec{r}_1 + t\vec{r}_2 \quad \forall t \in [0, 1]$$



A plane is determined by a point & a vector orthogonal to the plane.

$$\vec{r} - \vec{r}_0 = \vec{P_0P}$$

$$\vec{n} \perp \mathcal{P} \Rightarrow \vec{n} \cdot (\vec{r} - \vec{r}_0) = 0$$

$\vec{r} - \vec{r}_0$  is parallel to the plane

$$\vec{n} = \langle a, b, c \rangle \Rightarrow$$

$$\vec{n} \cdot (\vec{r} - \vec{r}_0) =$$

$$\langle a, b, c \rangle \cdot \langle x - x_0, y - y_0, z - z_0 \rangle$$

$$= a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$$

is the equation of the plane thru

$\vec{r}_0 = \langle x_0, y_0, z_0 \rangle$  that's perpendicular (orthogonal) to  $\vec{n} = \langle a, b, c \rangle$

$$\cos \theta = \frac{\vec{r} \cdot \vec{r}_0}{\|\vec{r}\| \|\vec{r}_0\|}$$

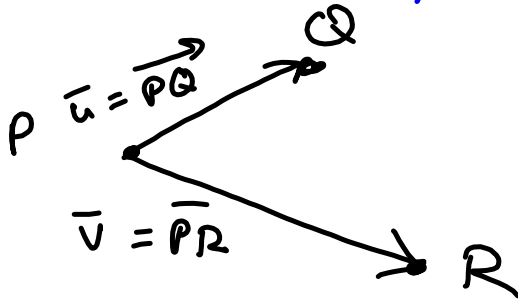
$$\psi = \text{psi:}$$

= angle between  $\vec{n}$  & the plane (to which  $\vec{r} - \vec{r}_0$  is parallel)

$$\cos \psi$$

Plane thru 3 points

$$P(1, -2, 3), Q(-5, 7, 11), R(1, 2, 3)$$



$$\vec{u} = \langle -6, 9, 8 \rangle$$

$$\vec{v} = \langle 0, 4, 0 \rangle$$

$$\vec{u} \times \vec{v} \quad \begin{array}{l} \langle -6, 9, 8 \rangle \times \langle 0, 4, 0 \rangle \\ \langle 0, 4, 0 \rangle \times \langle -6, 9, 8 \rangle \end{array}$$


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$$\langle -32, 0, -24 \rangle = \vec{n}^*$$

$\langle -4, 0, -3 \rangle$  is nicer.

Eq'n:  $\vec{n} \cdot (\vec{u} - \vec{r}_0)$

$$-4(x-1) + 0(y+2) - 3(z-3) = 0$$

$$-4(x-1) - 3(z-3) = 0$$