

16.9 Change of Variable(s) in Multiple Integrals

Recall the Substitution Rule with the variables reversed:

$$\int_a^b f(x) dx = \int_c^d f(g(u))g'(u) du$$

$$x = g(u) \text{ and } a = g(c), b = g(d)$$

$$\int_a^b f(x) dx = \int_c^d f(x(u)) \frac{dx}{du} du$$

$$\int_c^d f(u) du = \int_a^b f(g(x))g'(x) dx$$

$$\int_0^2 \cos(u) du = \int_0^1 \cos(2x) \cdot 2 dx$$

$$u = g(x) = 2x$$

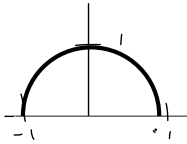
$$du = g'(x)dx = 2dx$$

$$x = 0 \Rightarrow u = 2 \cdot 0 = 0 = g(0)$$

$$x = 1 \Rightarrow u = 2 \cdot 1 = 2 = g(1)$$

Example: Trigonometric Substitution to simplify the integration process.

Find the area inside half a circle of radius $r = 1$.



$$x^2 + y^2 = 1$$

$$y^2 = 1 - x^2$$

$$y = \pm \sqrt{1 - x^2}$$

$$y = \sqrt{1 - x^2} \text{ is the top}$$

$$\text{Area} = \int_{-1}^1 \sqrt{1-x^2} dx$$

$$x = \cos \theta$$

$$dx = -\sin \theta d\theta$$

$$x = -1 = \cos \theta$$



$$\theta = \pi$$

$$x = 1 = \cos \theta$$

$$\theta = 0$$

$$\int_{\pi}^0 \sin \theta (-\sin \theta d\theta)$$

$$= - \int_{\pi}^0 \sin^2 \theta d\theta$$

$$= \int_0^{\pi} \frac{1 - \cos(2\theta)}{2} d\theta$$

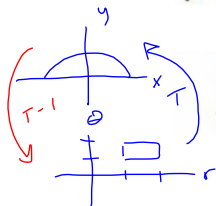
$$= \int_0^{\pi} \frac{1}{2} d\theta - \frac{1}{2} \cdot \frac{1}{2} \int_0^{\pi} \cos(2\theta) \cdot 2 d\theta$$

$$= \frac{1}{2}\pi - \frac{1}{4} [\sin 2\theta]_0^{\pi} = \frac{\pi}{2}$$

We've already extended this to double integrals and polar coordinates:

$$x = r \cos \theta$$

$$y = r \sin \theta$$



$$\iint_R f(x, y) dA = \iint_S f(r \cos \theta, r \sin \theta) r dr d\theta$$

is how we go from
 $dA = dx dy = dy dx$
 to
 $r dr d\theta$

JACOBIAN IS
 THE BRIDGE

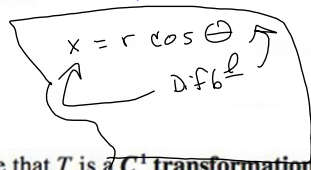
$$T(r, \theta) = (x, y)$$

The idea will be to
 Do a T^{-1} :

$$T(u, v) = (x, y)$$

$$T^{-1}(T(r, \theta)) = T^{-1}(x, y) = (r, \theta)$$

$$x = g(u, v)$$

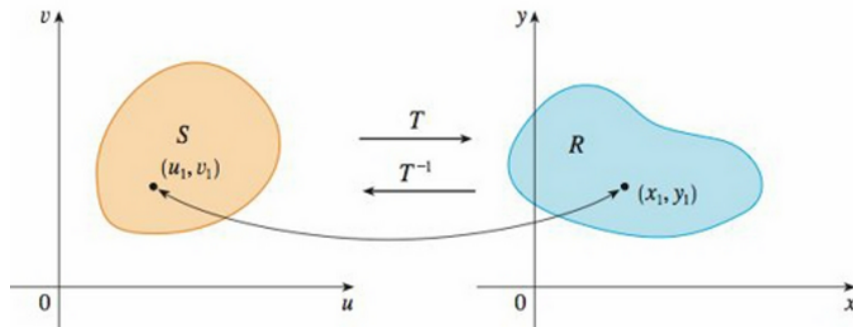


$$y = h(u, v)$$

We usually assume that T is a C^1 transformation, which means that g and h have continuous first-order partial derivatives.

Transformations (Mappings) from one domain *onto* another.

If $T(u_1, v_1) = (x_1, y_1)$, then the point (x_1, y_1) is called the **image** of the point (u_1, v_1)



$$u = G(x, y)$$

$$v = H(x, y)$$

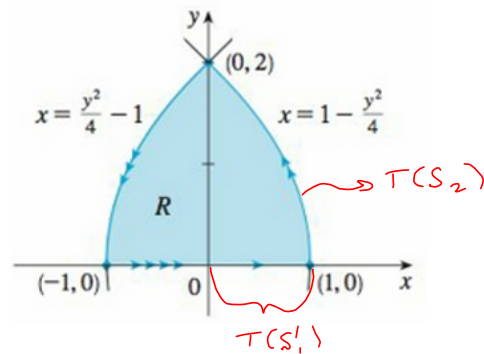
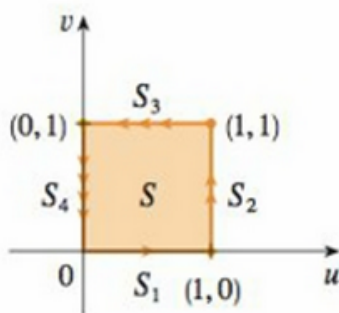
EXAMPLE 1 A transformation is defined by the equations

$$T^{-1}(x, y) = (u^2 - v^2, 2uv) \quad x = u^2 - v^2 \quad y = 2uv$$

Find the image of the square $S = \{(u, v) \mid 0 \leq u \leq 1, 0 \leq v \leq 1\}$

SOLUTION The transformation maps the boundary of S into the boundary of the image.

is reported as a fact, with no real proof, even though it is true.



$$T(S_1) : v = 0, 0 \leq u \leq 1$$

$$x = u^2 - v^2 = u^2 \quad y = 2uv = 0$$

$$\Rightarrow 0 \leq x \leq 1$$

$$T(S_2) : u = 1, 0 \leq v \leq 1$$

$$x = 1 - v^2, \quad y = 2v \Rightarrow v = \frac{1}{2}y$$

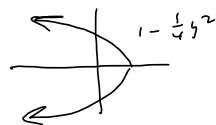
$$x = 1 - v^2 = 1 - \left(\frac{1}{2}y\right)^2 = 1 - \frac{1}{4}y^2$$

$$0 \leq v \leq 1$$

$$\& y = 2v \Rightarrow$$

$$0 \leq 2v \leq 2$$

$$0 \leq y \leq 2$$



$\iint_R f(x,y) dA$
 \downarrow
 $\iint_S f(u,v) dA$ *in terms of u,v.*

Tangent Line Segment to the boundary @ $(u_0, v_0) = \bar{r}(u_0, v_0)$

Derivation:
 $\Delta \bar{r} = \bar{b} = \bar{r}(u_0, v_0 + \Delta v) - \bar{r}(u_0, v_0)$
 $\Rightarrow \frac{\Delta \bar{r}}{\Delta v} = \frac{\bar{r}(u_0, v_0 + \Delta v) - \bar{r}(u_0, v_0)}{\Delta v} \approx \frac{d\bar{r}}{dv} = \bar{r}_v$
 $\Rightarrow \bar{b} = \bar{r}(u_0, v_0 + \Delta v) - \bar{r}(u_0, v_0)$
 $= \frac{\bar{r}(u_0, v_0 + \Delta v) - \bar{r}(u_0, v_0)}{\Delta v} \cdot \Delta v$
 $\approx \frac{d\bar{r}}{dv} \cdot \Delta v = \bar{r}_v \Delta v$
 $\bar{a} = \frac{d\bar{r}}{du} \cdot \Delta u = \bar{r}_u \Delta u$
 $\Rightarrow \|\bar{a} \times \bar{b}\| \approx \|(\bar{r}_u \Delta u) \times (\bar{r}_v \Delta v)\| = \|\bar{r}_u \times \bar{r}_v\| \Delta u \Delta v = dA$
 The increment of area for the conversion!

$$\iint_R f(x, y) dA = \iint_S f(x(u, v), y(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

7 DEFINITION The **Jacobian** of the transformation T given by $x = g(u, v)$ and $y = h(u, v)$ is

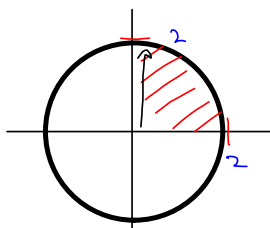
$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u}$$

↳ Area of the region R using mapping T & domain S !

Double Integral in Polar Coordinates. Where did the $r \, dr \, d\theta$ come from?

We know, but here we do it in terms of the new machinery:

$$\int_0^1 \int_0^{\sqrt{4-x^2}} (x^2 + y^2) \, dy \, dx$$



$$x = r \cos \theta, \quad y = r \sin \theta$$

$$T(r \cos \theta, r \sin \theta) = (x, y)$$

$$\vec{r}(r, \theta) = \langle r \cos \theta, r \sin \theta \rangle$$

$$\vec{r}_r = \langle \cos \theta, \sin \theta \rangle$$

$$\vec{r}_\theta = \langle -r \sin \theta, r \cos \theta \rangle$$

$$\|\vec{r}_r \times \vec{r}_\theta\|$$

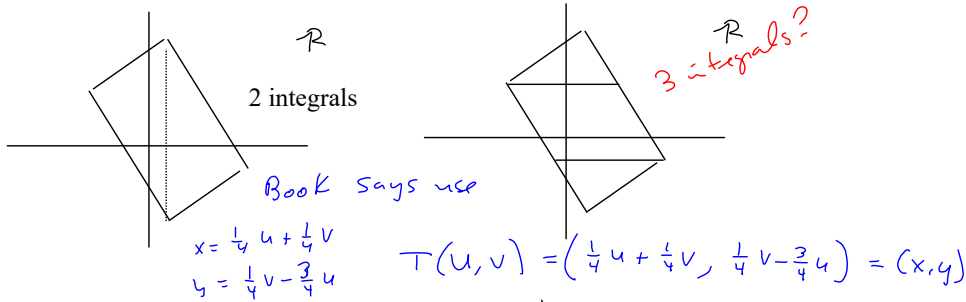
$$\begin{vmatrix} \cos \theta & \sin \theta \\ -r \sin \theta & r \cos \theta \end{vmatrix} = |r \cos^2 \theta + r \sin^2 \theta|$$

$$= |r| = r \quad \text{if } 0 \leq r$$

It's the r in the $r \, dr \, d\theta$!

#12

$\iint_R (4x+8y) dA$, where R is the parallelogram with corners $(-1,3), (1,-3), (3,-1), (1,5)$

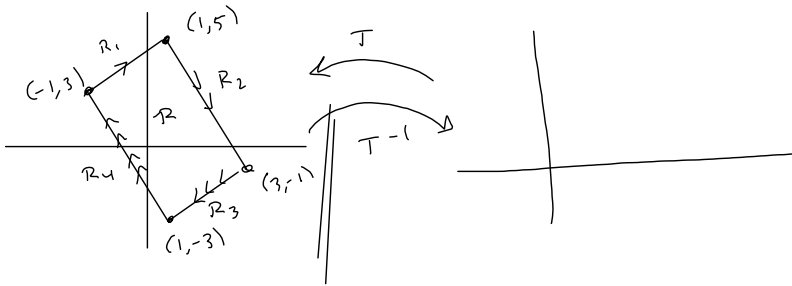


$\vec{r}(u,v) = \langle \frac{1}{4}u + \frac{1}{4}v, \frac{1}{4}v - \frac{3}{4}u \rangle$

$\vec{r}_u = \langle \frac{1}{4}, -\frac{3}{4} \rangle, \vec{r}_v = \langle \frac{1}{4}, \frac{1}{4} \rangle$

$\begin{vmatrix} \frac{1}{4} & -\frac{3}{4} \\ \frac{1}{4} & \frac{1}{4} \end{vmatrix} = \frac{1}{16} + \frac{3}{16} = \frac{4}{16} = \frac{1}{4} = \frac{2(x,y)}{2(u,v)}$

$4x + 8y = 4(\frac{1}{4}u + \frac{1}{4}v) + 8(\frac{1}{4}v - \frac{3}{4}u) = u + v + 2v - 6u = -5u + 3v$



To get T^{-1} , solve for u and v :

$x = \frac{1}{4}u + \frac{1}{4}v$
 $y = \frac{1}{4}v - \frac{3}{4}u$

$\frac{1}{4}u + \frac{1}{4}v = x \rightarrow \begin{bmatrix} \frac{1}{4} & \frac{1}{4} & | & x \\ -\frac{3}{4} & \frac{1}{4} & | & y \end{bmatrix}$

Reduced Row-Echelon Form: $\begin{bmatrix} 1 & 0 & | & x-y \\ 0 & 1 & | & 3x+y \end{bmatrix}$

$T^{-1} \rightarrow \begin{cases} u = x-y \\ v = 3x+y \end{cases}$

$(-1,3), (1,-3), (3,-1), (1,5)$

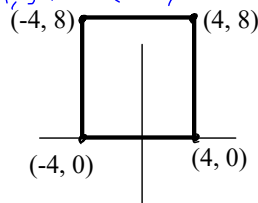
$T^{-1}(x,y) = (u,v) = (x-y, 3x+y)$

$T^{-1}(-1,3) = (-1-3, 3(-1)+3) = (-4,0)$

$T^{-1}(1,3) = (1-3, 3(1)-3) = (-2,0)$

$T^{-1}(3,-1) = (3-1, 3(3)+(-1)) = (2,10)$ No. $(3 - (-1), 3(3) + (-1)) = (4, 8)$

$T^{-1}(1,5) = (1-5, 3(1)+5) = (-4,8)$



1-6 Find the Jacobian of the transformation.

1. $x = 5u - v, y = u + 3v$ 2. $x = uv, y = u/v$

3. $x = e^{-r} \sin \theta, y = e^r \cos \theta$ 4. $x = e^{s+t}, y = e^{s-t}$

② $x = uv$

$x_u = v$

$x_v = u$

$y = \frac{u}{v} = uv^{-1}$

$y_u = v^{-1} = \frac{1}{v}$

$y_v = -uv^{-2} = -\frac{u}{v^2}$

$$\frac{d(x,y)}{d(u,v)} = \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} = \begin{vmatrix} v & u \\ v^{-1} & -uv^{-2} \end{vmatrix} = \begin{vmatrix} -uv^{-1} & -uv^{-1} \end{vmatrix}$$

$$\frac{d(x,y)}{d(u,v)} = \boxed{2 \frac{u}{v} = \frac{2u}{v} = 2uv^{-1}}$$

Just the determinant, NOT the absolute value of the determinant!

7-10 Find the image of the set S under the given transformation.

7. $S = \{(u, v) \mid 0 \leq u \leq 3, 0 \leq v \leq 2\};$

$x = 2u + 3v, y = u - v$

8. S is the square bounded by the lines $u = 0, u = 1, v = 0,$

$v = 1; x = v, y = u(1 + v^2)$

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(2) $x = uv$

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19-23 Evaluate the integral by making an appropriate change of variables.

19. $\iint_R \frac{x-2y}{3x-y} dA$, where R is the parallelogram enclosed by the lines $x-2y=0$, $x-2y=4$, $3x-y=1$, and $3x-y=8$

20. $\iint_R (x+y)e^{x^2-y^2} dA$, where R is the rectangle enclosed by the lines $x-y=0$, $x-y=2$, $x+y=0$, and $x+y=3$

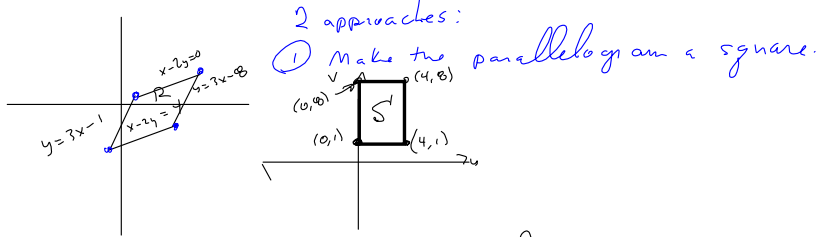
(19)

$$x-2y=0 \quad y=\frac{1}{2}x$$

$$x-2y=4$$

$$3x-y=1$$

$$3x-y=8$$



2 approaches:
 ① Make the parallelogram a square.

② Make a nice function

$$\frac{x-2y}{3x-y} \rightarrow \frac{u}{v}$$

This requires

finding $x(u,v)$ & $y(u,v)$

$$u = x-2y \quad T^{-1} = \begin{bmatrix} 1 & -2 \\ 3 & -1 \end{bmatrix}$$

$$v = 3x-y$$

Postulate $\frac{\partial(u,v)}{\partial(x,y)} = \frac{1}{\frac{\partial(x,y)}{\partial(u,v)}}$ $T?$

$$u_x = 1 \quad v_x = 3$$

$$u_y = -2 \quad v_y = -1$$

$$\begin{vmatrix} u_x & u_y \\ v_x & v_y \end{vmatrix} = \begin{vmatrix} 1 & -2 \\ 3 & -1 \end{vmatrix} = 5 \Rightarrow ?$$

We know that $\begin{bmatrix} 1 & -2 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} u \\ v \end{bmatrix}$

want $x = x(u,v)$
 $y = y(u,v)$

$$T^{-1} = \frac{1}{5} \begin{bmatrix} -1 & 2 \\ -3 & 1 \end{bmatrix}$$

$$T^{-1} \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix} = \frac{1}{5} \begin{bmatrix} -1u + 2v \\ -3u + v \end{bmatrix}$$

$$\Rightarrow x_u = -\frac{1}{5}, x_v = \frac{2}{5}$$

$$y_u = -\frac{3}{5}, y_v = \frac{1}{5}$$

NOTE This is not the same as $\frac{1}{5} \begin{vmatrix} -1 & 2 \\ -3 & 1 \end{vmatrix} = 1$

But $\frac{1}{25} \begin{vmatrix} -1 & 2 \\ -3 & 1 \end{vmatrix} = \frac{1}{5}$

$$\iint_R \frac{x-2y}{3x-y} dA$$

$$= \frac{1}{5} \int_0^4 \int_1^8 \frac{u}{v} dv du = \frac{1}{5} \int_0^4 \left[\frac{1}{2} \frac{u^2}{v} \right]_1^8 dv$$

$$= \frac{1}{5} \int_1^8 \frac{8}{v} dv = \frac{8}{5} \ln|v| \Big|_1^8 = \frac{8}{5} [\ln(8) - \ln(1)]$$

$$= \frac{8}{5} \ln(8)$$