

§16.9

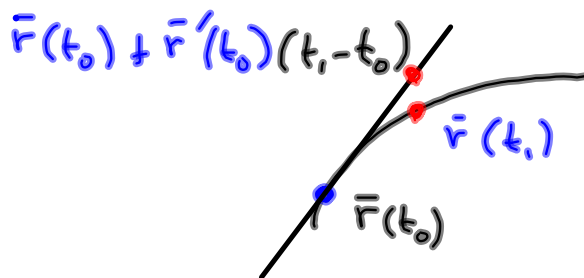
recall vector-valued functions,
defined parametrically

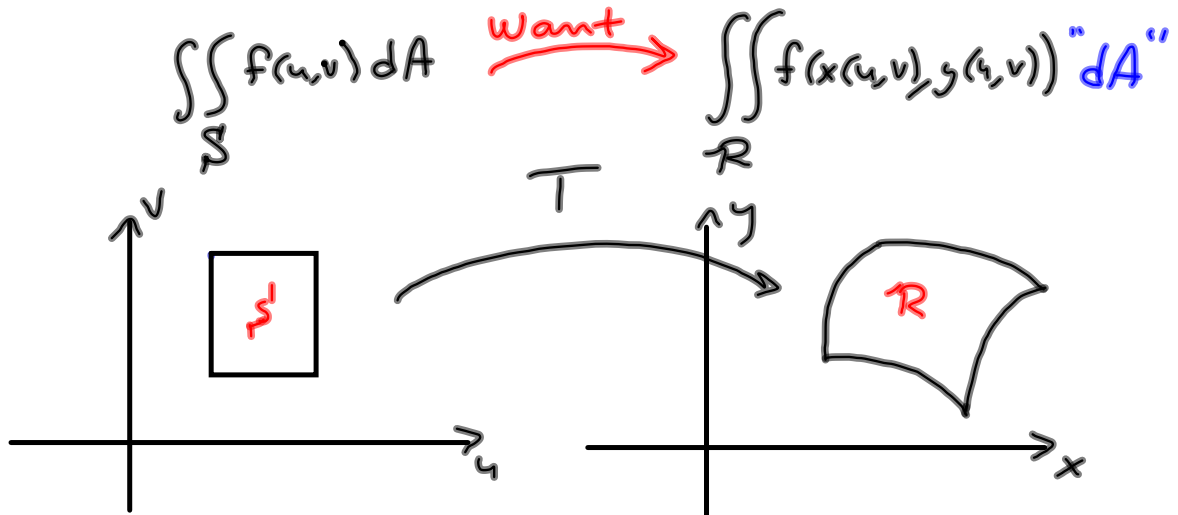
$$\vec{r}(t) = \langle x(t), y(t) \rangle$$

$$\vec{r}'(t) = \langle x'(t), y'(t) \rangle$$

Linear approximation

$$\begin{aligned}\vec{r}(t_1) &\approx \vec{r}(t_0) + \vec{r}'(t_0)(t_1 - t_0) \\ &= \vec{r}(t_0) + \vec{r}'(t_0)\Delta t\end{aligned}$$





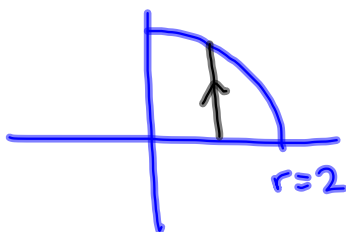
$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$T(u,v) = (x,y) = (x(u,v), y(u,v))$$

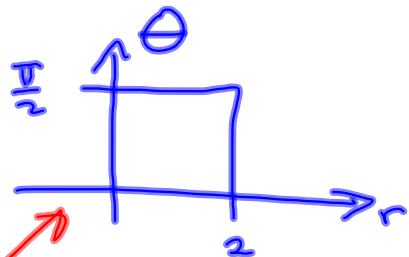
We've done stuff like this, already.

$$\iint (x^2+y^2) dy dx \rightarrow \iint r^2 \cdot r dr d\theta$$

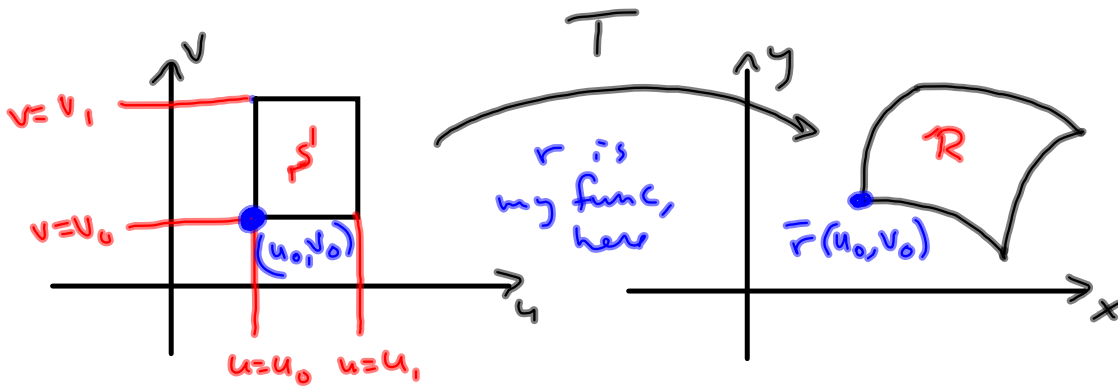
From rectangular to polar.



turns the quarter-circle in the xy-plane into a rectangle

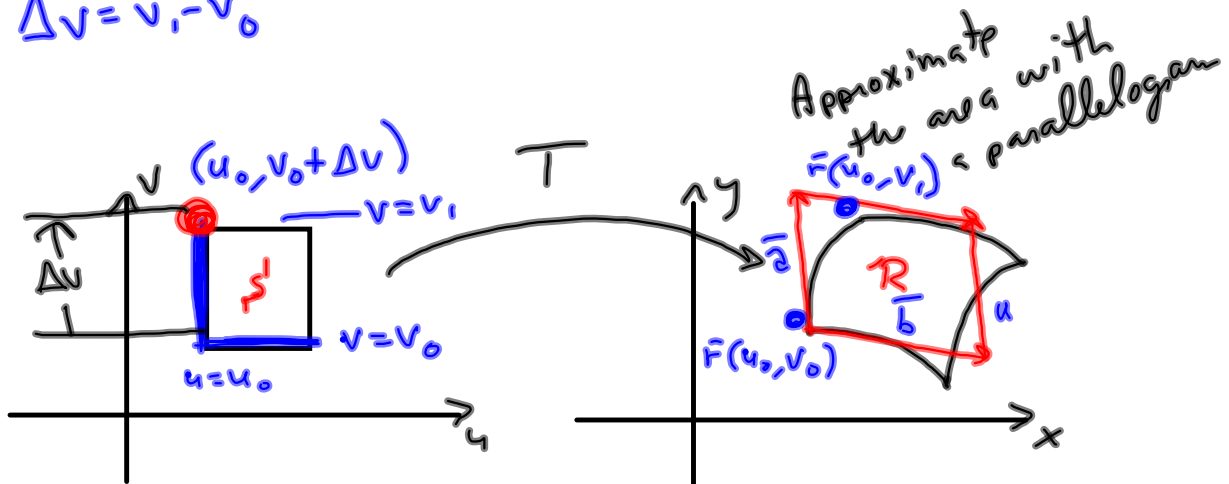


$$\int_0^2 \int_0^{\sqrt{4-x^2}} (x^2+y^2) dy dx \rightarrow \int_0^{\frac{\pi}{2}} \int_0^2 r^2 \cdot r dr d\theta$$



$$\Delta u = u_1 - u_0 \quad \vec{r}(u, v) = \langle x(u, v), y(u, v) \rangle$$

$$\Delta v = v_1 - v_0$$



Area of the parallelogram is $|\vec{a} \times \vec{b}|$

We "build" \vec{a} using linear approximation

See the two points $\vec{r}(u_0, v_0)$ & $\vec{r}(u_0, v)$

$$\vec{r}(u_0, v) = \vec{r}(u_0, v_0 + \Delta v)$$

$$\Delta \vec{r} = \vec{r}(u_0, v_0 + \Delta v) - \vec{r}(u_0, v_0)$$

$$\frac{\Delta \vec{r}}{\Delta v} = \frac{\vec{r}(u_0, v_0 + \Delta v) - \vec{r}(u_0, v_0)}{\Delta v} \approx \frac{d\vec{r}}{dv}$$

$$\text{So, } \bar{a} \approx \bar{r}(u_0, v_0 + \Delta v) - \bar{r}(u_0, v_0) \\ \approx \frac{d\bar{r}}{dv} \cdot \Delta v = \bar{r}_v \Delta v$$

Likewise, $\bar{b} \approx \bar{r}_u \Delta u$

$$\text{And so, } |\bar{a} \times \bar{b}| \approx |(\bar{r}_v \Delta v) \times (\bar{r}_u \Delta u)| \\ = |\bar{r}_v \times \bar{r}_u| \Delta v \Delta u$$

\approx Area of the region \mathcal{R} , using the mapping T of the domain \mathcal{S}

and so

$$\iint_{\mathcal{S}} f(u, v) dA \quad \text{Change of variables for double integrals.} \\ = \iint_{\mathcal{R}} f(x(u, v), y(u, v)) \underbrace{|\bar{r}_u \times \bar{r}_v|}_{\text{Jacobian}} du dv$$

$$\vec{r}_u \times \vec{r}_v = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ x_u & y_u & 0 \\ x_v & y_v & 0 \end{vmatrix} = (x_u y_v - x_v y_u) \vec{k}$$

$\vec{r}_u = \langle x_u, y_u \rangle$

$$\text{Jacobian} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ x_u & x_v & 0 \\ y_u & y_v & 0 \end{vmatrix} = (x_u y_v - x_v y_u) \vec{k}$$

And we just want its absolute value,
not its direction.

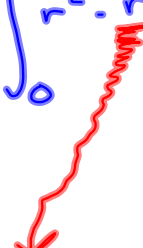
$$\boxed{D} \text{ Jacobian} = \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} = x_u y_v - x_v y_u$$

$$= \frac{\partial(x,y)}{\partial(u,v)}$$

$D7$

$$\Delta A = \left| \frac{\partial(x,y)}{\partial(u,v)} \right| \Delta u \Delta v$$

Convert

$$\int_0^1 \int_0^{\sqrt{4-x^2}} (x^2+y^2) dy dx = \int_0^{\frac{\pi}{2}} \int_0^2 r^2 \cdot r dr d\theta$$


$$\vec{r} = \langle x(r, \theta), y(r, \theta) \rangle$$

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases} \begin{cases} \vec{r}_r = \langle \cos \theta, \sin \theta \rangle \\ \vec{r}_\theta = \langle -r \sin \theta, r \cos \theta \rangle \end{cases}$$

$$\left| \frac{\partial(x, y)}{\partial(r, \theta)} \right| = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = \begin{vmatrix} x_r & x_\theta \\ y_r & y_\theta \end{vmatrix}$$

$$= |r \cos^2 \theta + r \sin^2 \theta|$$

$$= (r (\cos^2 \theta + \sin^2 \theta)) = |r| = r$$