

## 16.9 Change of Variable(s) in Multiple Integrals

Recall the Substitution Rule: THIS FIRST PAGE OF NOTES IS MESSED-UP. DON'T KNOW WHAT I WAS THINKING. WILL BE RE-WORKED, MONDAY...

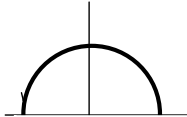
$$\int_a^b f(x) dx = \int_c^d f(g(u))g'(u) du$$

$$x = g(u) \text{ and } a = g(c), b = g(d)$$

$$\int_a^b f(x) dx = \int_c^d f(x(u)) \frac{dx}{du} du$$

Example: Trigonometric Substitution to simplify the integration process.

Find the area inside half a circle of radius  $r = 1$ .



We've already extended this to double integrals and polar coordinates:

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$\iint_R f(x, y) dA = \iint_S f(r \cos \theta, r \sin \theta) r dr d\theta$$

$$T(u, v) = (x, y)$$

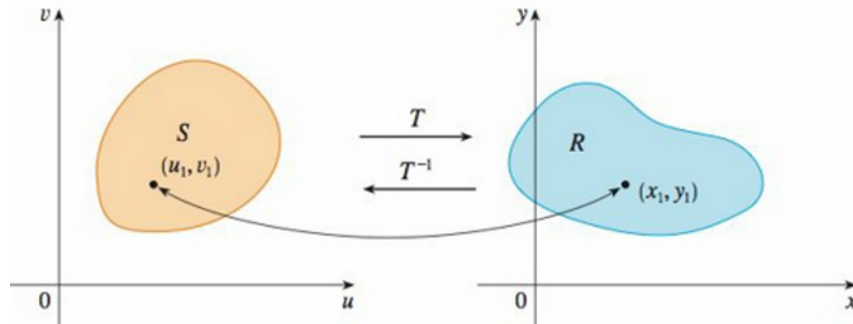
$$x = g(u, v)$$

$$y = h(u, v)$$

We usually assume that  $T$  is a  $C^1$  **transformation**, which means that  $g$  and  $h$  have continuous first-order partial derivatives.

Transformations (Mappings) from one domain *onto* another.

If  $T(u_1, v_1) = (x_1, y_1)$ , then the point  $(x_1, y_1)$  is called the **image** of the point  $(u_1, v_1)$



$$u = G(x, y)$$

$$v = H(x, y)$$

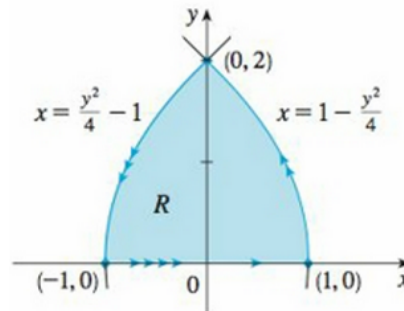
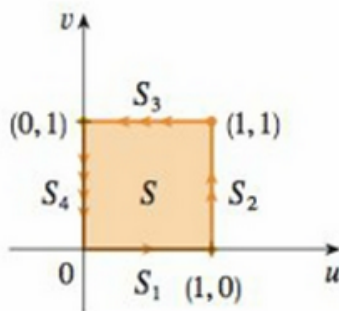
**EXAMPLE 1** A transformation is defined by the equations

$$x = u^2 - v^2 \quad y = 2uv$$

Find the image of the square  $S = \{(u, v) \mid 0 \leq u \leq 1, 0 \leq v \leq 1\}$

**SOLUTION** The transformation maps the boundary of  $S$  into the boundary of the image.

is reported as a fact, with no real proof, even though it is true.



$\iint_R f(x, y) dA$   
 $\downarrow$   
 $\iint_S f(u, v) dA$  *in terms of u, v.*

Area of parallelogram is  $\|\vec{a} \times \vec{b}\|$

**Derivation:**  
 $\Delta \vec{r} = \vec{b} = \vec{r}(u_0, v_0 + \Delta v) - \vec{r}(u_0, v_0)$   
 $\Rightarrow \frac{\Delta \vec{r}}{\Delta v} = \frac{\vec{r}(u_0, v_0 + \Delta v) - \vec{r}(u_0, v_0)}{\Delta v} \approx \frac{d\vec{r}}{dv} = \vec{r}_v$   
 $\Rightarrow \vec{b} = \vec{r}(u_0, v_0 + \Delta v) - \vec{r}(u_0, v_0)$   
 $= \frac{\vec{r}(u_0, v_0 + \Delta v) - \vec{r}(u_0, v_0)}{\Delta v} \cdot \Delta v$   
 $\approx \frac{d\vec{r}}{dv} \cdot \Delta v = \vec{r}_v \Delta v$   
 $\vec{a} = \frac{d\vec{r}}{du} \cdot \Delta u = \vec{r}_u \Delta u$   
 $\Rightarrow \|\vec{a} \times \vec{b}\| \approx \|(\vec{r}_u \Delta u) \times (\vec{r}_v \Delta v)\| = \|\vec{r}_u \times \vec{r}_v\| \Delta u \Delta v = dA$   
 The increment of area for the conversion!

$$\iint_R f(x, y) dA = \iint_S f(x(u, v), y(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

**7 DEFINITION** The **Jacobian** of the transformation  $T$  given by  $x = g(u, v)$  and  $y = h(u, v)$  is

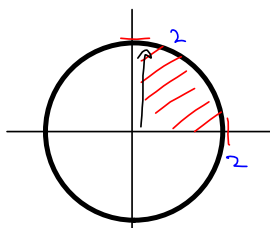
$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u}$$

*Area of the region  $R$  using mapping  $T$  & domain  $S$ !*

Double Integral in Polar Coordinates. Where did the  $r \, dr \, d\theta$  come from?

We know, but here we do it in terms of the new machinery:

$$\int_0^1 \int_0^{\sqrt{4-x^2}} (x^2 + y^2) \, dy \, dx$$



$$x = r \cos \theta, \quad y = r \sin \theta$$

$$T(r \cos \theta, r \sin \theta) = (x, y)$$

$$\vec{r}(r, \theta) = \langle r \cos \theta, r \sin \theta \rangle$$

$$\vec{r}_r = \langle \cos \theta, \sin \theta \rangle$$

$$\vec{r}_\theta = \langle -r \sin \theta, r \cos \theta \rangle$$

$$\|\vec{r}_r \times \vec{r}_\theta\|$$

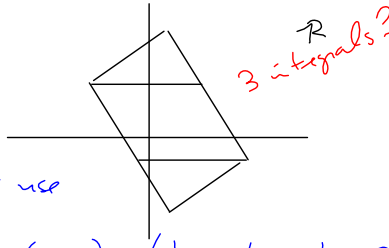
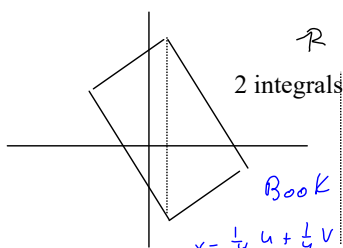
$$\begin{vmatrix} \cos \theta & \sin \theta \\ -r \sin \theta & r \cos \theta \end{vmatrix} = |r \cos^2 \theta + r \sin^2 \theta|$$

$$= |r| = r \quad \text{if } 0 \leq r$$

It's the  $r$  in the  $r \, dr \, d\theta$ !

#12

$\iint_R (4x+8y) dA$ , where  $R$  is the parallelogram with corners  $(-1,3), (1,-3), (3,-1), (1,5)$



Book says use  
 $x = \frac{1}{4}u + \frac{1}{4}v$   
 $y = \frac{1}{4}v - \frac{3}{4}u$

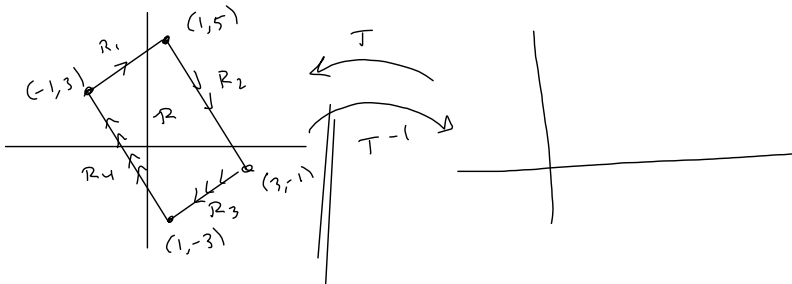
$T(u,v) = (\frac{1}{4}u + \frac{1}{4}v, \frac{1}{4}v - \frac{3}{4}u) = (x,y)$

$\vec{r}(u,v) = \langle \frac{1}{4}u + \frac{1}{4}v, \frac{1}{4}v - \frac{3}{4}u \rangle$

$\vec{r}_u = \langle \frac{1}{4}, -\frac{3}{4} \rangle, \vec{r}_v = \langle \frac{1}{4}, \frac{1}{4} \rangle$

$\begin{vmatrix} \frac{1}{4} & -\frac{3}{4} \\ \frac{1}{4} & \frac{1}{4} \end{vmatrix} = \frac{1}{16} + \frac{3}{16} = \frac{4}{16} = \frac{1}{4} = \frac{2(x,y)}{2(u,v)}$

$4x + 8y = 4(\frac{1}{4}u + \frac{1}{4}v) + 8(\frac{1}{4}v - \frac{3}{4}u)$   
 $= u + v + 2v - 6u = -5u + 3v$



To get  $T^{-1}$ , solve for  $u$  and  $v$ :

$x = \frac{1}{4}u + \frac{1}{4}v$   
 $y = \frac{1}{4}v - \frac{3}{4}u$

$\frac{1}{4}u + \frac{1}{4}v = x \rightarrow \begin{bmatrix} \frac{1}{4} & \frac{1}{4} & | & x \\ -\frac{3}{4} & \frac{1}{4} & | & y \end{bmatrix}$

Reduced Row-Echelon Form:  $\begin{bmatrix} 1 & 0 & | & x-y \\ 0 & 1 & | & 3x+y \end{bmatrix}$

$T^{-1} \rightarrow \begin{cases} u = x-y \\ v = 3x+y \end{cases}$

$(-1,3), (1,-3), (3,-1), (1,5)$

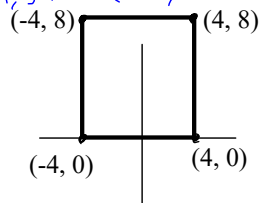
$T^{-1}(x,y) = (u,v) = (x-y, 3x+y)$

$T^{-1}(-1,3) = (-1-3, 3(-1)+3) = (-4,0)$

$T^{-1}(1,3) = (1-3, 3(1)-3) = (-2,0)$

$T^{-1}(3,-1) = (3-1, 3(3)+(-1)) = (2,8)$  No.  $(3 - (-1), 3(3)+(-1)) = (4,8)$

$T^{-1}(1,5) = (1-5, 3(1)+5) = (-4,8)$



**1-6** Find the Jacobian of the transformation.

1.  $x = 5u - v, y = u + 3v$     2.  $x = uv, y = u/v$

3.  $x = e^{-r} \sin \theta, y = e^r \cos \theta$     4.  $x = e^{s+t}, y = e^{s-t}$

(2)  $x = uv$

$$x_u = v$$

$$x_v = u$$

$$y = \frac{u}{v} = uv^{-1}$$

$$y_u = v^{-1} = \frac{1}{v}$$

$$y_v = -uv^{-2} = -\frac{u}{v^2}$$

$$\frac{\partial(x,y)}{\partial(u,v)} = \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} = \begin{vmatrix} v & u \\ v^{-1} & -uv^{-2} \end{vmatrix} = |-uv^{-1} - uv^{-1}|$$

$$\frac{\partial(x,y)}{\partial(u,v)} = \boxed{2 \frac{u}{v} = \frac{2u}{v} = 2uv^{-1}}$$

**7-10** Find the image of the set  $S$  under the given transformation.

7.  $S = \{(u, v) \mid 0 \leq u \leq 3, 0 \leq v \leq 2\};$

$$x = 2u + 3v, y = u - v$$

8.  $S$  is the square bounded by the lines  $u = 0, u = 1, v = 0, v = 1; x = v, y = u(1 + v^2)$

**11-16** Use the given transformation to evaluate the integral.

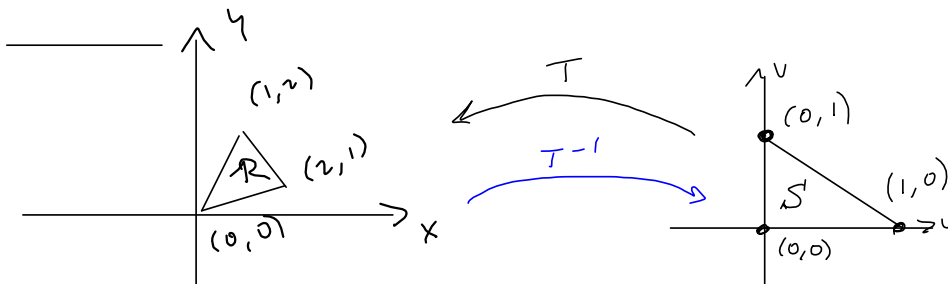
II.  $\iint_R (x - 3y) dA$ , where  $R$  is the triangular region with vertices  $(0, 0)$ ,  $(2, 1)$ , and  $(1, 2)$ ;  $x = 2u + v$ ,  $y = u + 2v$

Def'n: A linear transformation  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  satisfies

$$T(a\vec{u} + b\vec{v}) = aT(\vec{u}) + bT(\vec{v})$$

FACT: Any linear transformation  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  can be represented by a matrix-times-vector product, i.e.,  $T$  is a matrix!

$$\text{Define } T = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} 2u + 1v \\ 1u + 2v \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix}$$



$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$b = 1$$

$$d = 2$$

$$T = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$a = 2$$

$$c = 1$$

$$\text{So } T = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

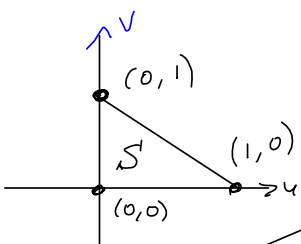


$$\begin{array}{ll} x = 2u + v & y = u + 2v \\ x_u = 2 & y_u = 1 \\ x_v = 1 & y_v = 2 \end{array} \quad \frac{\partial(x,y)}{\partial(u,v)} = \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} = \begin{vmatrix} 2 & 1 \\ 1 & 2 \end{vmatrix} = 3$$

$$\iint_R (x-3y) dA = \iint_{S'} (2u+v - 3(u+2v)) (3 du dv)$$

$$2u + v - 3u - 6v = -u - 5v$$

$$= -3 \iint_{S'} (u+5v) du dv$$



$$= -3 \int_0^1 \int_0^{1-u} (u+5v) dv du$$

$$= -3 \int_0^1 \int_0^{1-v} (u+5v) du dv$$

$$v = 1 - u \Rightarrow u = 1 - v$$

$$= -3 \int_0^1 \left[ uv + \frac{5}{2} v^2 \right]_0^{1-u} du = -3 \int_0^1 \left( u(1-u) + \frac{5}{2} (1-u)^2 \right) du$$

$$u - u^2 + \frac{5}{2}(u^2 - 2u + 1) = u - u^2 + \frac{5}{2}u^2 - 5u + \frac{5}{2}$$

$$= \frac{3}{2}u^2 - 4u + \frac{5}{2}$$

$$= -3 \int_0^1 \left( \frac{3}{2}u^2 - 4u + \frac{5}{2} \right) du = -3 \left[ \frac{1}{2}u^3 - 2u^2 + \frac{5}{2}u \right]_0^1$$

$$-3 \left[ \frac{1}{2} - 2 + \frac{5}{2} \right] = \boxed{-3}$$

**19-23** Evaluate the integral by making an appropriate change of variables.

19.  $\iint_R \frac{x-2y}{3x-y} dA$ , where  $R$  is the parallelogram enclosed by the lines  $x-2y=0$ ,  $x-2y=4$ ,  $3x-y=1$ , and  $3x-y=8$

20.  $\iint_R (x+y)e^{x^2-y^2} dA$ , where  $R$  is the rectangle enclosed by the lines  $x-y=0$ ,  $x-y=2$ ,  $x+y=0$ , and  $x+y=3$

(19)

$x-2y=0 \implies y=\frac{1}{2}x$

x	y
0	0

$x-2y=4$

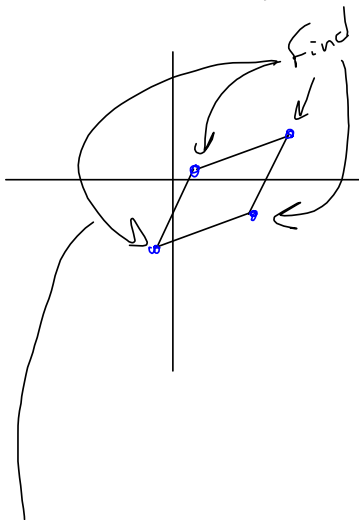
x	y
0	-2
4	0

$3x-y=1$

x	y
0	-1
$\frac{1}{3}$	0

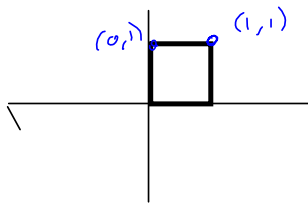
$3x-y=8$

x	y
0	-8
$\frac{8}{3}$	0



2 approaches:

① Make the parallelogram a square.



② Make a nice function

$$\frac{x-2y}{3x-y} \longrightarrow \frac{u}{v}$$

This requires finding  $x(u,v)$  &  $y(u,v)$

$$u = x - 2y$$

$$v = 3x - y \quad T^{-1} \bullet \begin{bmatrix} 1 & -2 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 4 \\ 1 \end{bmatrix}$$

$$\text{Want } (x, y) = T(u, v)$$

Invert the matrix!

$$\left[ \begin{array}{cc|cc} 1 & -2 & 1 & 0 \\ 3 & -1 & 0 & 1 \end{array} \right] \begin{array}{l} r_1 \\ -3r_1 + r_2 \end{array} \rightarrow \left[ \begin{array}{cc|cc} 1 & -2 & 1 & 0 \\ 0 & 5 & -3 & 1 \end{array} \right]$$

$$\therefore \text{ So } T = \begin{bmatrix} -\frac{1}{5} & \frac{2}{5} \\ -\frac{3}{5} & \frac{1}{5} \end{bmatrix} = \frac{1}{5} \begin{bmatrix} -1 & 2 \\ -3 & 1 \end{bmatrix}$$

Cramer's Rule

$$\frac{1}{|A|} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

~~$$T = \begin{bmatrix} 1 & 2 \\ 3 & -1 \end{bmatrix}$$~~

~~$$T^{-1} = \frac{1}{-2} \begin{bmatrix} 4 & -2 \\ -3 & 1 \end{bmatrix}$$~~

↓ This says that

$$x = -\frac{1}{5}u + \frac{2}{5}v$$

$$y = -\frac{3}{5}u + \frac{1}{5}v$$

$$\begin{vmatrix} -\frac{1}{5} & \frac{2}{5} \\ -\frac{3}{5} & \frac{1}{5} \end{vmatrix} = -\frac{1}{25} - \frac{6}{25} = -\frac{7}{25} = -\frac{1}{5}$$

$$\iint_S \frac{u}{v} \cdot \frac{1}{5} du dv$$

$$\rightarrow \begin{bmatrix} 1 & -2 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = \begin{bmatrix} u_1 \\ v_1 \end{bmatrix}$$

will tell you  
the corner points  
of  $S$

